

# BRUSHLESS DC PLANETARY GEAR MOTOR DM-36RPBL3650

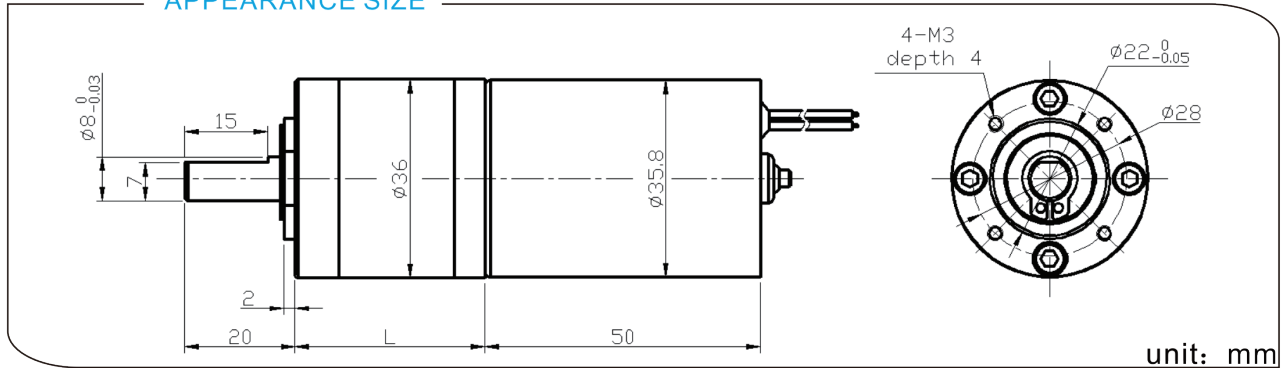
典型应用/Typical applications :

自动快锁门、装订机、自动电视架、点钞机、聚光灯、卫生纸机、  
办公设备、家用电器、自动执行机构

Auto shutter, binding machine, automatic TV rack, money counter,  
spotlight, tissue machine, office equipments, household appliances,  
automatic actuator



## APPEARANCE SIZE



## 齿轮箱参数/Gearbox Data:

级数 Number of stages	1	2	3	4	5
减数比 Reduction Ratio i	3.7、5.2	14、19、27	51、71、100 139	189、264、369 515、721	977、1367、1910
齿轮箱长度 Gearbox Length L (mm)	26.5	34.7	42.9	51.1	59.3
破坏扭力 Breaking Torque(kgf.cm)	10	18	40	50	60
齿轮箱效率 Gearbox Efficiency $\eta$	90%	81%	73%	65%	59%

## 电机参数/Driving Motor Data:

DC Motor Model	Rated	No Load		Max Efficiency Load			Stall		
	电压	电流	转速	电流	转速 (nm)	扭矩 (tm)	功率	扭矩	电流
	Volt.	Current	Speed	Current	Speed	Torque	P.out	Torque	Current
	V	mA	r/min	mA	r/min	gf.cm	W	gf.cm	mA
DM-BL3650-012-3000	12	≤170	3000	≤775	2400	100	2.5	≥510	≥2340
DM-BL3650-012-4500	12	≤260	4500	≤1160	3300	150	5.1	≥768	≥3520
DM-BL3650-012-6000	12	≤340	6000	≤1550	4500	200	9.2	≥1020	≥4680
DM-BL3650-024-3000	24	≤140	3000	≤600	2400	100	2.5	≥510	≥1200
DM-BL3650-024-4500	24	≤210	4500	≤900	3300	150	5.1	≥768	≥1760

## 减数电机参数/Geared Motor Data :

Gear Motor Model	额定电压 Rated voltage	No load		Max Efficiency Load			Stall		
		电流	转速	电流	转速 (n)	扭矩 (t)	功率	扭矩	电流
		Current	Speed	Current	Speed	Torque	P.out	Torque	Current
	V	A	r/min	A	r/min	kgf.cm	W	kgf.cm	A
DM-36RPBL3650-0093000-264K	9	0.15	11.3	0.46	8.3	13	1.12	49	1.32
DM-36RPBL3650-0126000-3.7K	12	0.29	1577.6	1.47	1303.5	0.83	11.04	4.75	7.06
DM-36RPBL3650-0128000-369K	12	0.44	22	1.84	17.1	41	7.24	186	6.76
DM-36RPBL3650-0246000-51K	24	0.16	113.9	0.78	97.5	9.2	9.27	64.3	4.47

电机参数仅供参考, 请以实际样板为准; 可以依据客户要求定制参数。

The motor parameters are for reference only, please refer to real measured data;

We can customize parameters according to customer requirements.

减数电机输出转速=直流电机输出转速/齿轮箱减数比; 减数电机输出扭矩=直流电机输出扭矩\*齿轮箱减数比\*齿轮箱传动效率。

Gear Motor Output Speed=DC Motor Speed/Gear Ratio ( $n=n_m/i$ )

Gear Motor Output Torque=DC Motor Torque\*Gear Ratio\*Gearbox Efficiency. ( $t=t_m*i*\eta$ )